

# Unit testing with pytest and nose<sup>1</sup>

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Unit testing is widely a used technique for verifying software implementation. The idea is to identify small units of code and test each unit, ideally in a way such that one test does not depend on the outcome of other tests. Several tools, often referred to as testing frameworks, exist for automatically running all tests in a software package and report if any test failed. The value of such tools during software development cannot be exaggerated. Below we describe how to write tests that can be used by either the nose<sup>2</sup> or the pytest<sup>3</sup> testing frameworks. Both these have a very low barrier for beginners, so there is no excuse for not using nose or pytest as soon as you have learned about functions in programming.

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<sup>1</sup>The material in this document is taken from a chapter in the book *A Primer on Scientific Programming with Python*, 4th edition, by the same author, published by Springer, 2014.

<sup>2</sup><https://nose.readthedocs.org/>

<sup>3</sup><http://pytest.org/latest/>

## Contents

**Model software.** We need a piece of software we want to test. Here we choose a function that runs Newton's method for solving algebraic equations  $f(x) = 0$ . A very simple implementation goes like

```
def Newton_basic(f, dfdx, x, eps=1E-7):
    n = 0 # iteration counter
    while abs(f(x)) > eps:
        x = x - f(x)/dfdx(x)
        n += 1
    return x, f(x), n
```

## 1 Requirements of the test function

The simplest way of using the pytest or nose testing frameworks is to write a set of test functions, scattered around in files, such that pytest or nose can automatically find and run all the test functions. To this end, the test functions need to follow certain conventions.

### Test function conventions.

1. The name of a test function starts with `test_`.
2. A test function cannot take any arguments.
3. Any test must be formulated as a boolean condition.
4. An `AssertionError` exception is raised if the boolean condition is false (i.e., when the test fails).

There are many ways of raising the `AssertionError` exception:

```
# Formulate a test
tol = 1E-14 # comparison tolerance for real numbers
success = abs(reference - result) < tol
msg = 'computed_result=%d != %d' % (result, reference)

# Explicit raise
if not success:
    raise AssertionError(msg)

# assert statement
assert success, msg
```

```
# nose tools
import nose.tools as nt
nt.assert_true(success, msg)
# or
nt.assert_almost_equal(result, reference, msg=msg, delta=tol)
```

This book contains a lot of test functions following the conventions of the `pytest` and `nose` testing frameworks, and we almost exclusively use the plain `assert` statement to have full control of what the test method is. In more complicated software the many functions in `nose.tools` may save quite some coding and are convenient to use.

## 2 Writing the test function; precomputed data

Newton's method for solving an algebraic equation  $f(x) = 0$  results in only an approximate root  $x_r$ , making  $f(x_r) \neq 0$ , but  $|f(x_r)| \leq \epsilon$ , where  $\epsilon$  is supposed to be a prescribed number close to zero. The problem is that we do not know beforehand what  $x_r$  and  $f(x_r)$  will be. However, if we strongly believe the function we want to test is correctly implemented, we can record the output from the function in a test case and use this output as a reference for later testing.

Assume we try to solve  $\sin(x) = 0$  with  $x = -\pi/3$  as start value. Running `Newton_basic` with a moderate-size `eps` ( $\epsilon$ ) of  $10^{-2}$  gives  $x = 0.000769691024206$ ,  $f(x) = 0.000769690948209$ , and  $n = 3$ . A test function can now compare new computations with these reference results. Since new computations on another computer may lead to round-off errors, we must compare real numbers with a small tolerance:

```
def test_Newton_basic_precomputed():
    from math import sin, cos, pi

    def f(x):
        return sin(x)

    def dfdx(x):
        return cos(x)

    x_ref = 0.000769691024206
    f_x_ref = 0.000769690948209
    n_ref = 3

    x, f_x, n = Newton_basic(f, dfdx, x=-pi/3, eps=1E-2)

    tol = 1E-15 # tolerance for comparing real numbers
    assert abs(x_ref - x) < tol # is x correct?
    assert abs(f_x_ref - f_x) < tol # is f_x correct?
    assert n == 3 # is n correct?
```

The `assert` statements involving comparison of real numbers can alternatively be carried out by `nose.tools` functionality:

```
nose.tools.assert_almost_equal(x_ref, x, delta=tol)
```

For simplicity we dropped the optional messages explaining what went wrong if tests fail.

### 3 Writing the test function; exact numerical solution

Approximate numerical methods are sometimes exact in certain special cases. An exact answer known beforehand is a good starting point for a test since the implementation should reproduce the known answer to machine precision. For Newton's method we know that it finds the exact root of  $f(x) = 0$  in one iteration if  $f(x)$  is a linear function of  $x$ . This fact leads us to a test with  $f(x) = ax + b$ , where we can choose  $a$  and  $b$  freely, but it is always wise to choose numbers different from 0 and 1 since these have special arithmetic properties that can hide programming errors.

The test function contains the problem setup, a call to the function to be verified, and `assert` tests on the output, this time also with an error message in case tests fail:

```
def test_Newton_basic_linear():
    """Test that a linear function is handled in one iteration."""
    f = lambda x: a*x + b
    dfdx = lambda x: a
    a = 0.25; b = -4
    x_exact = 16
    eps = 1E-5
    x, f_x, n = Newton_basic(f, dfdx, -100, eps)

    tol = 1E-15 # tolerance for comparing real numbers
    assert abs(x - 16) < tol, 'wrong root x=%g != 16' % x
    assert abs(f_x) < eps, '|f(root)|=%g > %g' % (f_x, eps)
    assert n == 1, 'n=%d, but linear f should have n=1' % n
```

### 4 Testing of function robustness

Our `Newton_basic` function is very basic and suffers from several problems:

- for divergent iterations it will iterate forever,
- it can divide by zero in  $f(x)/dfdx(x)$ ,
- it can perform integer division in  $f(x)/dfdx(x)$ ,
- it does not test whether the arguments have acceptable types and values.

A more robust implementation dealing with these potential problems look as follows:

```

def Newton(f, dfdx, x, eps=1E-7, maxit=100):
    if not callable(f):
        raise TypeError(
            'f is %s, should be function or class with __call__'
            % type(f))
    if not callable(dfdx):
        raise TypeError(
            'dfdx is %s, should be function or class with __call__'
            % type(dfdx))
    if not isinstance(maxit, int):
        raise TypeError('maxit is %s, must be int' % type(maxit))
    if maxit <= 0:
        raise ValueError('maxit=%d <= 0, must be > 0' % maxit)

    n = 0 # iteration counter
    while abs(f(x)) > eps and n < maxit:
        try:
            x = x - f(x)/float(dfdx(x))
        except ZeroDivisionError:
            raise ZeroDivisionError(
                'dfdx(%g)=%g - cannot divide by zero' % (x, dfdx(x)))
        n += 1
    return x, f(x), n

```

The numerical functionality can be tested as described in the previous example, but we should include additional tests for testing the additional functionality. One can have different tests in different test functions, or collect several tests in one test function. The preferred strategy depends on the problem. Here it may be natural to have different test functions only when the  $f(x)$  formula differs to avoid repeating code.

To test for divergence, we can choose  $f(x) = \tanh(x)$ , which is known to lead to divergent iterations if not  $x$  is sufficiently close to the root  $x = 0$ . A start value  $x = 20$  reveals that the iterations are divergent, so we set `maxit=12` and test that the actual number of iterations reaches this limit. We can also add a test on  $x$ , e.g., that  $x$  is as big as we know it will be:  $x > 10^{50}$  after 12 iterations. The test function becomes

```

def test_Newton_divergence():
    from math import tanh
    f = tanh
    dfdx = lambda x: 10./(1 + x**2)

    x, f_x, n = Newton(f, dfdx, 20, eps=1E-4, maxit=12)
    assert n == 12
    assert x > 1E+50

```

To test for division by zero, we can find an  $f(x)$  and an  $x$  such that  $f'(x) = 0$ . One simple example is  $x = 0$ ,  $f(x) = \cos(x)$ , and  $f'(x) = -\sin(x)$ . If  $x = 0$  is the start value, we know that a division by zero will take place in the first iteration, and this will lead to a `ZeroDivisionError` exception. We can explicitly handle this exception and introduce a boolean variable `success` that is `True` if the exception is raised and otherwise `False`. The corresponding test function reads

```

def test_Newton_div_by_zero1():
    from math import sin, cos
    f = cos
    dfdx = lambda x: -sin(x)
    success = False
    try:
        x, f_x, n = Newton(f, dfdx, 0, eps=1E-4, maxit=1)
    except ZeroDivisionError:
        success = True
    assert success

```

There is a special `nose.tools.assert_raises` helper function that can be used to test if a function raises a certain exception. The arguments to `assert_raises` are the exception type, the name of the function to be called, and all positional and keyword arguments in the function call:

```

import nose.tools as nt

def test_Newton_div_by_zero2():
    from math import sin, cos
    f = cos
    dfdx = lambda x: -sin(x)
    nt.assert_raises(
        ZeroDivisionError, Newton, f, dfdx, 0, eps=1E-4, maxit=1)

```

Let us proceed with testing that wrong input is caught by function `Newton`. Since the same type of exception is raised for different type of errors we shall now also examine (parts of) the exception messages. The first test involves an argument `f` that is not a function:

```

def test_Newton_f_is_not_callable():
    success = False
    try:
        Newton(4.2, 'string', 1.2, eps=1E-7, maxit=100)
    except TypeError as e:
        if "f is <type 'float'>" in e.message:
            success = True

```

As seen, `success = True` demands that the right exception is raised and that its message starts with `f is <type 'float'>`. What text to expect in the message is evident from the source in function `Newton`.

The `nose.tools` module also has a function for testing the exception type and the message content. This is illustrated when `dfdx` is not callable:

```

def test_Newton_dfdx_is_not_callable():
    nt.assert_raises_regexp(
        TypeError, "dfdx is <type 'str'>",
        Newton, lambda x: x**2, 'string', 1.2, eps=1E-7, maxit=100)

```

Checking that `Newton` catches `maxit` of wrong type or with a negative value can be carried out by these test functions:

```

def test_Newton_maxit_is_not_int():
    nt.assert_raises_regex(
        TypeError, "maxit is <type 'float'>",
        Newton, lambda x: x**2, lambda x: 2*x,
        1.2, eps=1E-7, maxit=1.2)

def test_Newton_maxit_is_neg():
    nt.assert_raises_regex(
        ValueError, "maxit=-2 <= 0",
        Newton, lambda x: x**2, lambda x: 2*x,
        1.2, eps=1E-7, maxit=-2)

```

The corresponding support for testing exceptions in pytest is

```

import pytest
with pytest.raises(TypeError) as e:
    Newton(lambda x: x**2, lambda x: 2*x, 1.2, eps=1E-7, maxit=-2)

```

## 5 Automatic execution of tests

Our code for the `Newton_basic` and `Newton` functions is placed in a file `eq_solver.py`<sup>4</sup> together with the tests. To run all test functions with names of the form `test_*` in this file, use the `nosetests` or `py.test` commands, e.g.,:

---

Terminal

---

```

Terminal> nosetests -s eq_solver.py
.....
-----
Ran 10 tests in 0.004s

OK

```

---

The `-s` option causes all output from the called functions in the program `eq_solver.py` to appear on the screen (by default, `nosetests` and `py.test` suppress all output). The final `OK` points to the fact that no test failed. Adding the option `-v` prints out the outcome of each individual test function. In case of failure, the `AssertionError` exception and the associated message, if existing, are displayed. Pytest also displays the code that failed.

One can also collect test functions in separate files with names starting with `test`. A simple command `nosetests -s -v` will look for all such files in this folder as well as in all subfolders if the folder names start with `test` or end with `_test` or `_tests`. By following this naming convention, `nosetests` can automatically run a potentially large number of tests and give us quick feedback. The `py.test -s -v` command will look for and run all test files in the entire tree of *any* subfolder.

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<sup>4</sup>[http://tinyurl.com/pwyasaa/tech/eq\\_solver.py](http://tinyurl.com/pwyasaa/tech/eq_solver.py)

**Remark on classical class-based unit testing.**

The pytest and nose testing frameworks allow ordinary functions, as explained above, to perform the testing. The most widespread way of implementing unit tests, however, is to use class-based frameworks. This is also possible with nose and with a module `unittest` that comes with standard Python. The class-based approach is very accessible for people with experience from JUnit in Java and similar tools in other languages. Without such a background, plain functions that follow the pytest/nose conventions are faster and cleaner to write than the class-based counterparts.



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